Multi-Spacecraft Coherent Doppler and Winging for Interplanetary Navigation

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Abstract

1 uture interplanetary mission concepts are increasingly focusing on multi-spacecraft missions and on mall sample return missions which may involve the rendezvous between a spacecraft which brings a sample from the surface of a solar system body and a spacecraft which will return the sample to the Earth. These types of missions place tight requirements on the knowledge of the relative positions of the spacecraft. I listorically spacecraft positions have been determind by the use of radio metric data (1 Doppler and range) bet ween the spacecraft and terrestrial receiving stations. The USC of two independent spacecraftto ground radio links for multi-spacecraft missions is inefficient in its usage of limited ground resources and frequently does not provide an adequate determination of the relative spat'co aftpositions. Use of radio metric data originating on one spacecraft which is then received, processed, and either telemetered to the Larth or processed on board can provide a more di rect measurement of spacecraft relative positions. Such a system was carried aboard the Mars Observer spacecraft as part of the Mars Balloon Relay package that was to track Russian Mars landers. However, these systems place a tight requirements on the stability of onboard frequency standards on both spacecraft and on the precision of the data extraction hardware on the spacecraft,

An alternative is to extend lhe coherent ground to spat'cci aft link through one spaceci aft to the other and then to the ground or back through the fill st spacecraft and to the ground receiver. Although initially appearing to complicate the separation of the dynamics of the two spacecraft, this paper will show that in actual application, judicious selection of spacecraft transponder frequency ratios and the use of coherent J Doppler and ranging and the derived observable, 1 DRVIID (1 Differenced Range vs. J Integrated 1 Doppler) can allow for the generation of observable equations which are dominated by the spacecraft to spacecraft link. This is due to the fact that although transponder frequency ratios affect the Doppler observable they do not affect the ranging observable. Consequently, these ratios can be chosen such that the effect on a DRVIID observable of a path length change over one link can be maximized, while the effect of other links can be minimized. Numerical analysis shows that this pi{n'ides significantly improved navigation capability, over telemetered systems and multiple Farth to spacecraft links, while decreasing the demands on the spacecraft hardware capabilities.